

# Split-explicit methods and local linear splitting

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# Time scales

Time scales in the atmosphere, flow

- Sound waves 340m/s
- Gravity waves 100m/s
- Wind speed 60m/s

Use time integration methods which use different time steps for different

$$y' = f(y) + g(y)$$

## Compressible Euler equations

$$\frac{\partial(\rho\mathbf{v})}{\partial t} + \nabla(\rho\mathbf{v}\mathbf{v}) - \nabla\boldsymbol{\tau} = -\nabla p - \rho g\mathbf{k} - 2\boldsymbol{\Omega} \times (\rho\mathbf{v})$$

$$\frac{\partial\rho}{\partial t} + \nabla(\rho\mathbf{v}) = 0$$

$$\frac{\partial(\rho\theta)}{\partial t} + \nabla(\rho\theta\mathbf{v}) - \nabla(\rho\mathbf{K}_\theta\nabla\theta) = Q_\theta$$

$$\frac{\partial(\rho\mu)}{\partial t} + \nabla(\rho\mu\mathbf{v}) - \nabla(\rho\mathbf{K}_\mu\nabla\mu) = Q_\mu$$

$$p = \left( \frac{R_d\rho\theta}{p_0^\kappa} \right)^{1/(1-\kappa)}$$

- Pressure is determined by equation of state:  $p = P(\rho, \theta, \mathbf{c})$
- Moist potential temperature  $\theta$
- In the dry case  $\theta = T \left( \frac{p_0}{p} \right)^\kappa$  with  $\kappa \equiv R_d/c_{pd} = \text{const.}$

# Splitting nonlinear equation

$$\begin{aligned}
 \frac{\partial \rho}{\partial t} &= -\frac{\partial \rho u}{\partial x} - \frac{\partial \rho w}{\partial z} \\
 \frac{\partial \rho u}{\partial t} &= -\frac{\partial \rho u u}{\partial x} - \frac{\partial \rho w u}{\partial z} - \frac{\partial p}{\partial x} \\
 \frac{\partial \rho w}{\partial t} &= -\frac{\partial \rho u w}{\partial x} - \frac{\partial \rho w w}{\partial z} - \frac{\partial p}{\partial z} - \rho g \\
 \frac{\partial \rho \theta}{\partial t} &= -\frac{\partial \rho u \theta}{\partial x} - \frac{\partial \rho w \theta}{\partial z}
 \end{aligned}$$

$$\dot{y} = F(y, y)$$

## Splitting nonlinear "linearized" equation

$$\begin{aligned} \frac{\partial \rho}{\partial t} &= -\frac{\partial \rho u}{\partial x} - \frac{\partial \rho w}{\partial z} \\ \frac{\partial \rho u}{\partial t} &= -\frac{\partial \rho u u}{\partial x} - \frac{\partial \rho w u}{\partial z} - \frac{\partial p}{\partial \rho \theta} \frac{\partial \rho \theta}{\partial x} \\ \frac{\partial \rho w}{\partial t} &= -\frac{\partial \rho u w}{\partial x} - \frac{\partial \rho w w}{\partial z} - \frac{\partial p}{\partial \rho \theta} \frac{\partial \rho \theta}{\partial z} - \rho g \\ \frac{\partial \rho \theta}{\partial t} &= -\frac{\partial \rho u \theta}{\partial x} - \frac{\partial \rho w \theta}{\partial z} \end{aligned}$$



$$\dot{y} = F(y) + A(y)y$$

# Splitting linearized equation

- The approximate, quasi-Boussinesq linearized equations

$$u_t = -Uu_x - c_s p_x$$

$$w_t = -Uw_x - c_s p_z - N\theta$$

$$\theta_t = -U\theta_x - Nw$$

$$p_t = -Up_x - c_s(u_x + w_z)$$

- One dimensional acoustic advection system

$$u_t = -Uu_x - c_s p_x$$

$$p_t = -Up_x - c_s u_x$$

# Split system

$$\dot{u} = f_u(u) + g_p(p)$$

$$\dot{p} = f_p(p) + g_u(u)$$

- Slow system

$$\dot{u} = f_u(u)$$

$$\dot{p} = f_p(p)$$

- Integrated with a Runge-Kutta method
- Fast system

$$\dot{u} = g_p(p)$$

$$\dot{p} = g_u(u)$$

- Integrated with symplectic Euler (Forward-Backward)



# Underlying Runge-Kutta

- Wicker and Skamarock (MWR 2002) used a three-stage Runge-Kutta method as slow integrator:

$$u^{n+1/3} = u^n + \frac{\Delta t}{3} f_u(u^n)$$

$$p^{n+1/3} = p^n + \frac{\Delta t}{3} f_p(p^n)$$

$$u^{n+1/2} = u^n + \frac{\Delta t}{2} f_u(u^{n+1/3})$$

$$p^{n+1/2} = p^n + \frac{\Delta t}{2} f_p(p^{n+1/3})$$

$$u^{n+1} = u^n + \Delta t f_u(u^{n+1/2})$$

$$p^{n+1} = p^n + \Delta t f_p(p^{n+1/2})$$

## Split-explicit

- Resulting splitting scheme:

$$u = u^n, \quad p = p^n$$

for  $k = 1 : n_s/3$

$$u = u + \Delta\tau g_u(p) + \Delta\tau f_u(u^n)$$

$$p = p + \Delta\tau g_p(u) + \Delta\tau f_p(p^n)$$

end

$$u^{n+1/3} = u, \quad p^{n+1/3} = p, \quad u = u^n, \quad p = p^n$$

for  $k = 1 : n_s/2$

$$u = u + \Delta\tau g_u(p) + \Delta\tau f_u(u^{n+1/3})$$

$$p = p + \Delta\tau g_p(u) + \Delta\tau f_p(p^{n+1/3})$$

end

$$u^{n+1/2} = u, \quad p^{n+1/2} = p, \quad u = u^n, \quad p = p^n$$

for  $k = 1 : n_s$

$$u = u + \Delta\tau g_u(p) + \Delta\tau f_u(u^{n+1/2})$$

$$p = p + \Delta\tau g_p(u) + \Delta\tau f_p(p^{n+1/2})$$

end

# General split-explicit methods

- Assume that we can solve the fast part of

$$\dot{y} = f(y) + g(y)$$

"exact"

- Then a split Runge–Kutta method reads:

$$Z_{ni}(0) = y_n$$

$$\dot{Z}_{ni}(\tau) = \frac{1}{c_i} \sum_{j=1}^{i-1} a_{ij} f(Y_{nj}) + g(Z_{ni}(\tau))$$

$$Y_{ni} = Z_{ni}(c_i h)$$

$$y_{n+1} = Y_{n,s+1}$$

- For the nonlinear case

$$\dot{Z}_{ni}(\tau) = \frac{1}{c_i} \sum_{j=1}^{i-1} a_{ij} F(Y_{nj}, Z_{ni}(\tau))$$

# The method

- We generalize the exact integration procedure in two directions:
  - arbitrary starting points based on preceding stages

$$Z_{ni}(t_n + \epsilon_{i-1}\Delta t) = y_n + \sum_{j=1}^{i-1} \alpha_{ij}(Y_{nj} - y_n)$$

- increments in the constant term  $F$  based on preceding stages

$$\dot{Z}_{ni}(\tau) = \frac{1}{\delta_i} \left( \sum_{j=1}^{i-1} \gamma_{ij}(Y_{nj} - y_n) + \sum_{j=1}^{i-1} \beta_{ij} f(Y_{nj}) \right) + g(Z_{ni}(\tau))$$

- Intermediate time intervals for local integration

$$\tau \in [y_n + \epsilon_{i-1}\Delta t, y_n + \epsilon_i\Delta t]$$

- New set of parameters, includes standard Runge-Kutta methods

## Phi function and linear equations

Other names: Exponential time differencing (ETD)

$$\dot{y} = N(y) + Ly, \quad (1)$$

Assume

$$N(y(t+h)) = \sum_{k=0}^{m-1} \frac{h^k}{k!} N_k$$

then (1) has the solution

$$y(t+h) = \sum_{k=1}^m h^k \phi_k(hL) N_{k-1} + \exp(hL)y(t)$$

with

$$\phi_k(z) = \frac{\phi_{k-1}(z) - 1/(k-1)!}{z}$$

# The split explicit method

Apply the split-explicit method to (1)

$$Y_1 = y_n$$

$$Y_2 = \exp(1/3hL)y_n + h\phi_1(1/3hL)N(Y_1)$$

$$Y_3 = \exp(1/2hL)y_n + h\phi_1(1/2hL)N(Y_2)$$

$$y_{n+1} = \exp(hL)y_n + h\phi_1(hL)N(Y_3)$$

## Exponential Rosenbrock-like methods

Now use with

$$J_n = f'(y_n) + g'(y_n)$$

$$N(y) = f(y) + g(y) - J_n y$$

$$L = J_n$$

- New coefficients
- Partitioned methods or W-methods with  $J_n = g'(y_n)$

## Idea

- Splitting by adding and subtracting a linear term
- $y' = F(y) = Ly + (F(Y) - Ly) = Ly + f(y)$
- Split the linear term again in two parts  $L = L_E + L_I$
- A sub step in the split explicit method reads
$$Z' = L_E Z + L_I Z + r$$
- Apply an implicit-explicit method (IMEX) to this linear equation



## IMEX-Methods

- Partitioned Runge-Kutta methods for additive splitting
- One method explicit, second diagonal implicit (DIRK)

$c_2$	$a_{21}$			$\bar{c}_1$	$\bar{\gamma}$		
$c_3$	$a_{31}$	$a_{32}$		$\bar{c}_2$	$\bar{a}_{21}$	$\bar{\gamma}$	
	$b_1$	$b_2$	$b_3$	$\bar{c}_3$	$\bar{a}_{31}$	$\bar{a}_{32}$	$\bar{\gamma}$
					$\bar{b}_1$	$\bar{b}_2$	$\bar{b}_3$

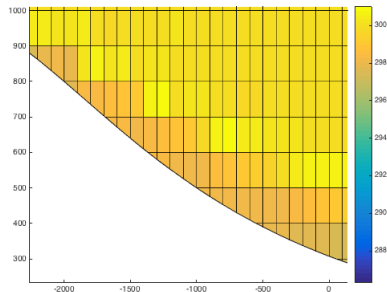
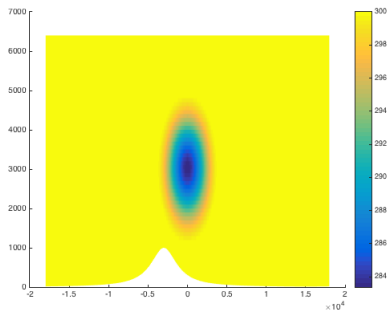
$$Z_i = Z_0 + \Delta\tau \sum_{j=1}^{i-1} a_{ij} L_E Z_j + \Delta\tau \sum_{j=1}^{i-1} \bar{a}_{ij} L_I Z_j + \Delta\tau \hat{\gamma} L_I Z_i$$

$$(I - \Delta\tau \hat{\gamma} L_I) Z_i = Z_0 + \Delta\tau L_E \sum_{j=1}^{i-1} a_{ij} Z_j + \Delta\tau L_I \sum_{j=1}^{i-1} \bar{a}_{ij} Z_j$$

- Per step two matrix vector multiplications and one linear solve

# Straka-test with orography

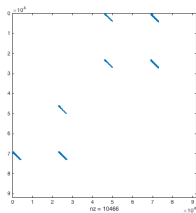
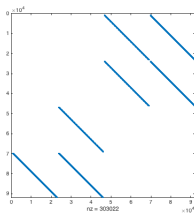
- Cut cell grid
- 36000 m in the horizontal, 6400 m in the vertical, grid size 100 m



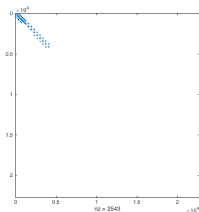
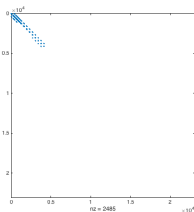
- Linear part: Acoustic for the whole domain and advection near cut cells
- Linear implicit part: Acoustic and advection near cut cells

# Fill in structure

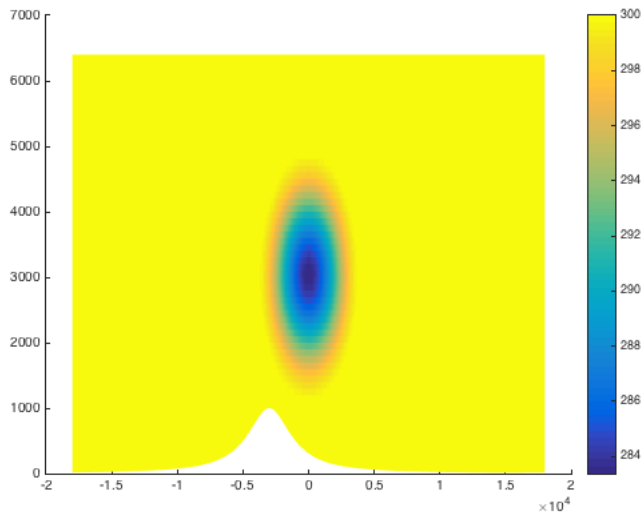
- Fill in explicit versus implicit part for linear acoustic



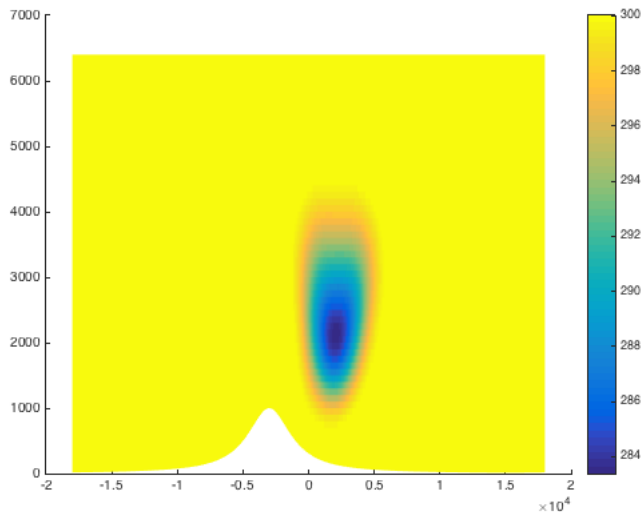
- Fill in implicit part for advection, scalar and vertical wind



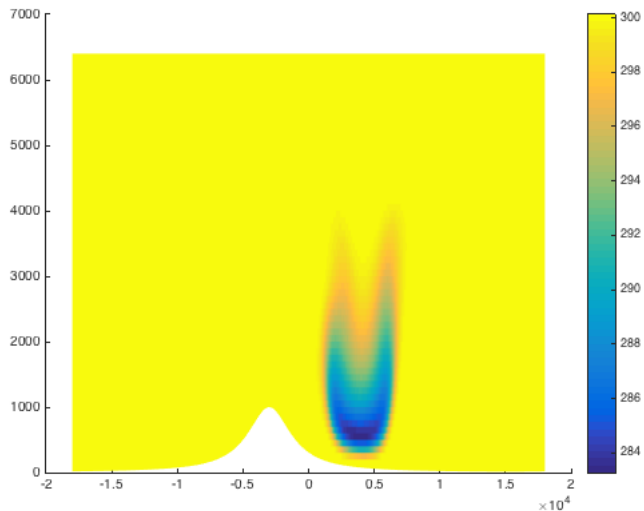
## Cold bubble



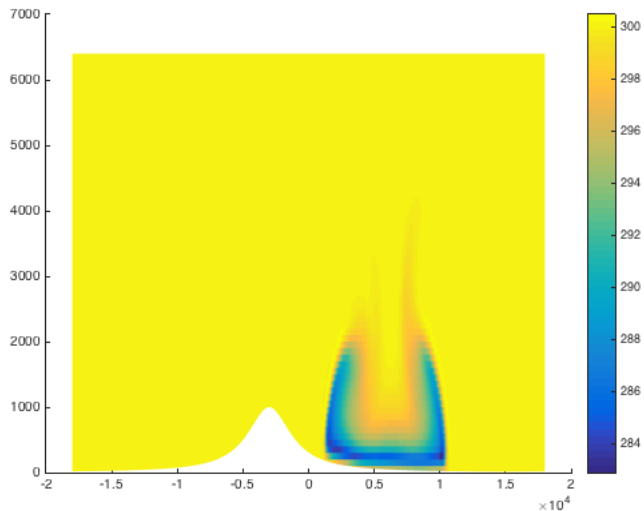
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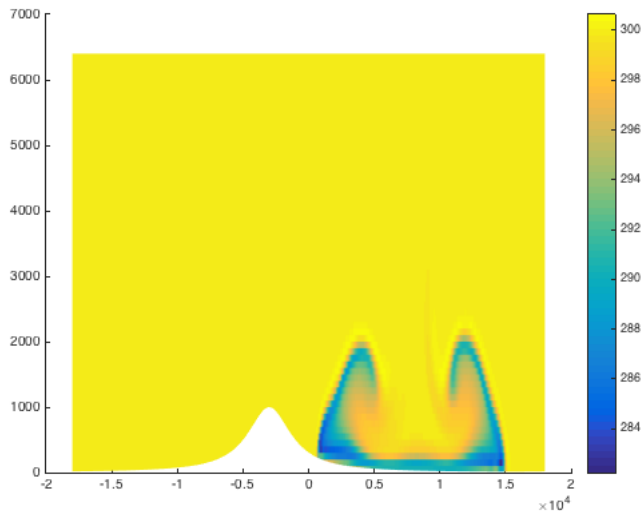
## Cold bubble



## Cold bubble

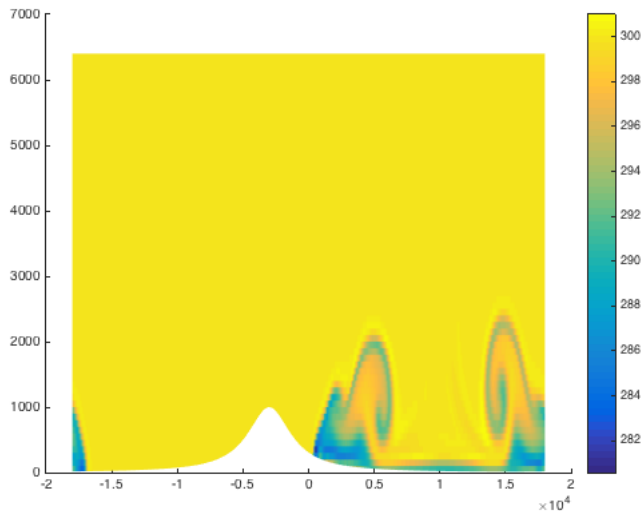


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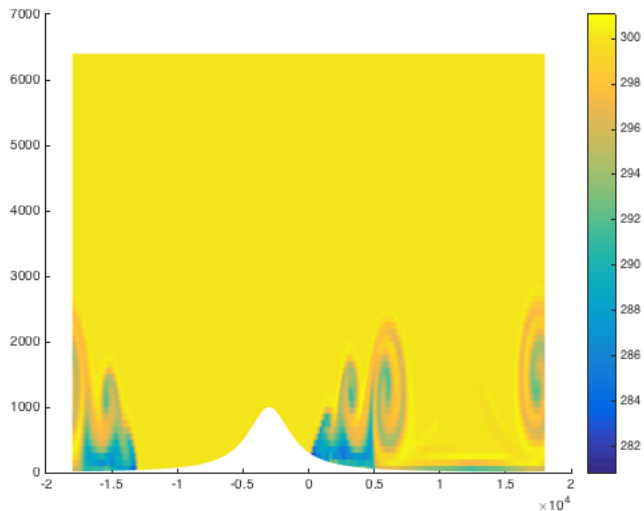




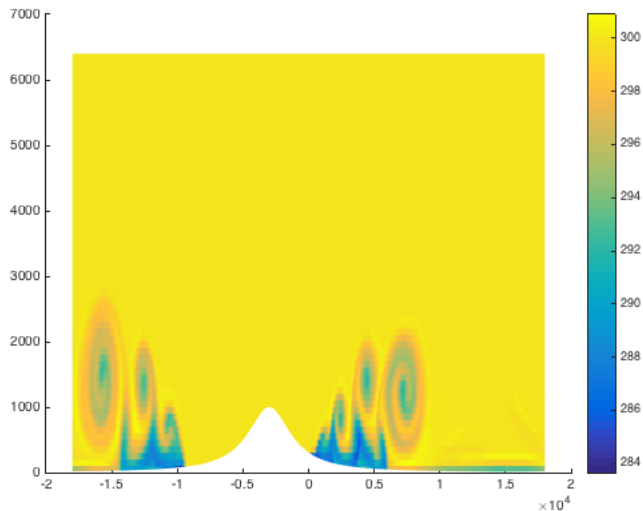
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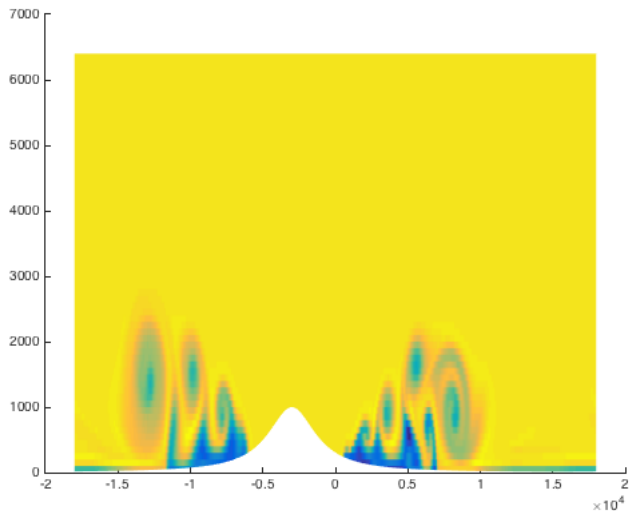
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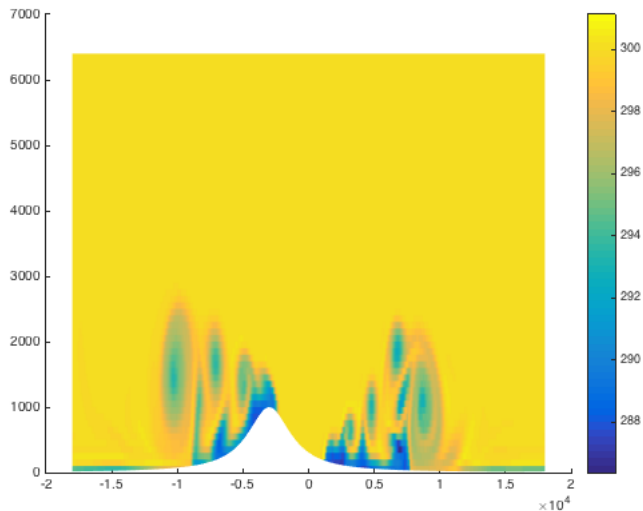
## Cold bubble



## Cold bubble

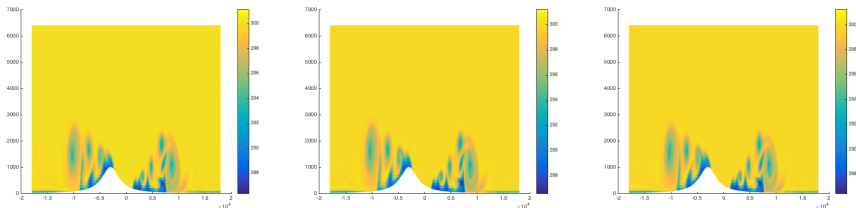


## Cold bubble



## Cold bubble

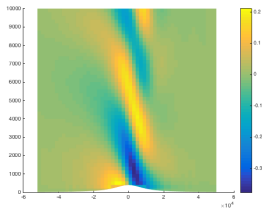
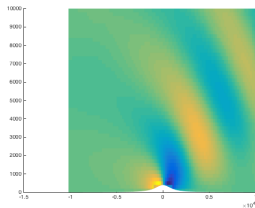
- Cold bubble with large time step of 1 s, 2 s, and 3 s.



dt	Small time steps			
1	3	3	2	4
2	6	6	3	8
3	8	8	4	11

# Example of Gallus/Klemp

- Flow over hill of 400m of a stratified flow
- Nonhydrostatic case  $\Delta x = 200\text{m}$  and  $\Delta x = 100\text{m}$
- Hydrostatic case  $\Delta x = 2000\text{m}$  and  $\Delta x = 100$
- First case only cut cells implicit,  $\Delta t = 20\text{s}$
- Number of small time steps, 23, 21, 11, 32
- Second case cut cells and vertical direction for acoustic,  $\Delta t = 100\text{s}$
- Number of small time steps 9, 8, 4, 12



# Conclusions

- Split-explicit methods are a special exponential integrator
- Room for new methods
- Can be used for cut cell grids with small additional overhead
- Numerical examples demonstrate theory



# Future work

- Automatic choice of implicit part
- Efficient implementation for parallel application
  - Organize computation for sub vectors
  - New data structure for exchange for data
- Tests for global examples