

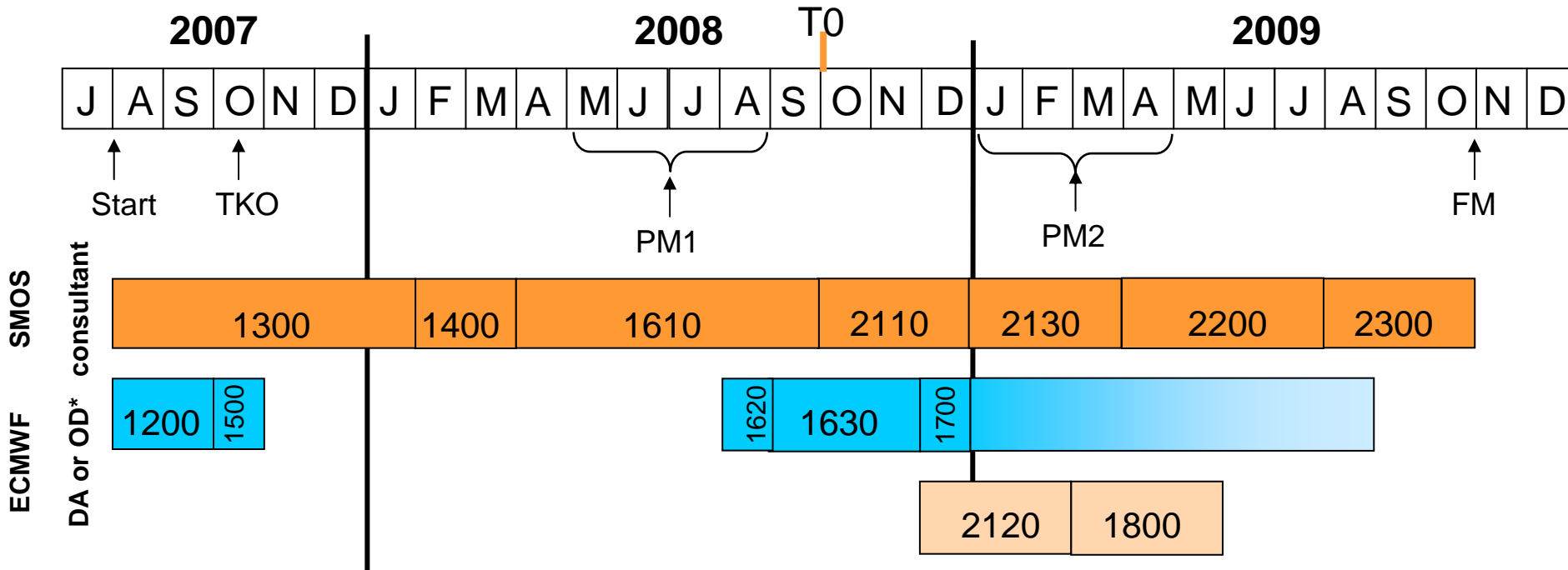
SMOS Data Assimilation Study: Introduction and Preparatory Work

ECMWF

Phase I to III

- **Monitoring of Level 1c brightness temperatures and assimilation of brightness temperatures over land**
 - ❑ 27 months, August 2007 - October 2009
 - ❑ 15 WPs: 7 WPs (ESA, 27 woman months) + 8 WPs (ECMWF, 14 man months)
 - ❑ Part I: NRT monitoring of global brightness temperatures.
 - ❑ Part II: Evaluation of the possible impact of SMOS measurements on the weather forecast quality.
- **Assimilation of SMOS derived surface soil moisture**
- **Assimilation of SMOS derived surface salinity**

Schedule Phase I



Part I: Monitoring - Comparing the Model Against Observations

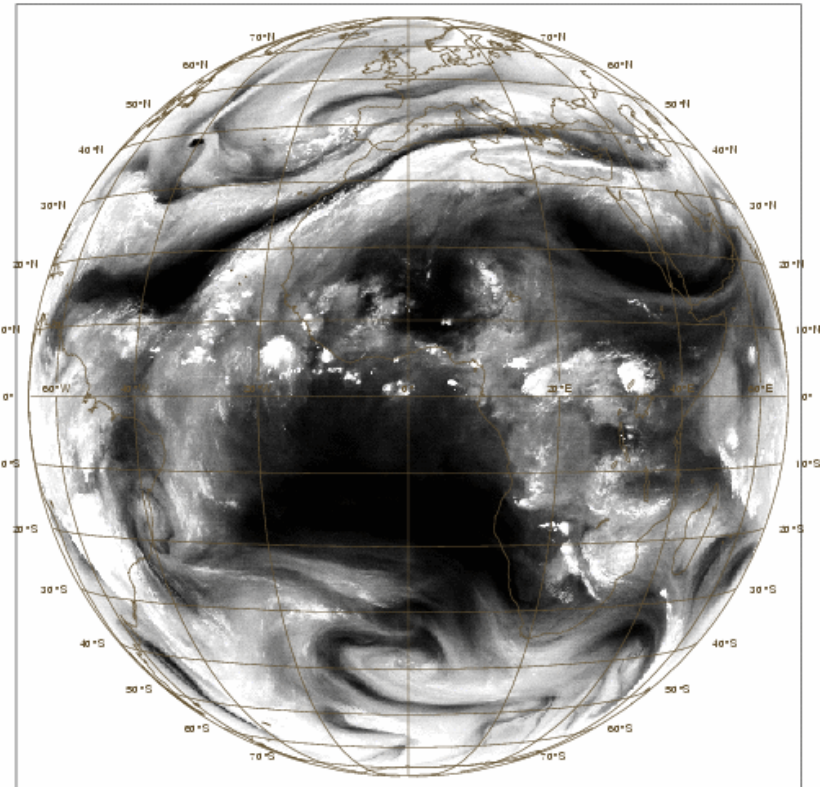
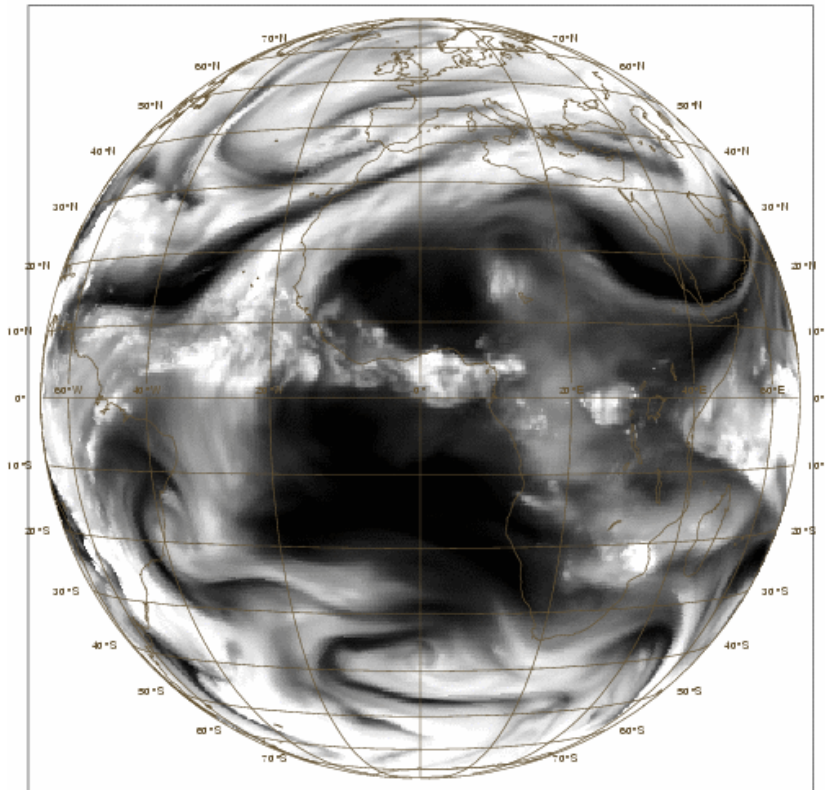
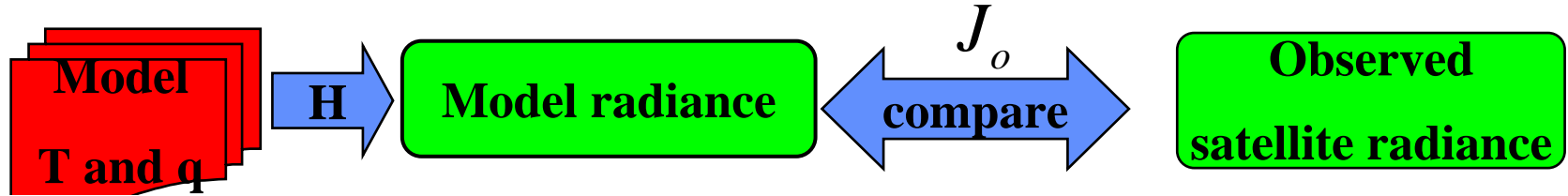
General idea:

- Observations are not generally available at model grid points and do not support the same spatial scale.
- Satellites measure radiances/brightness temperatures/reflectivities, etc., NOT directly temperature, soil moisture, or ozone.
- A model equivalent of the observation is calculated to enable comparison.
- This is done with the 'observation operator' H :

H may be a simple interpolation from model grid to observation location for direct observations, for example, of winds or temperature from radiosondes

H may possibly perform additional complex transformations of model variables to, for example, satellite radiances.

A Monitoring Example



Meteosat imagery

The SMOS Observation Operator

WP 1100: Sensitivity study on auxiliary data sets

WP 1200: Ocean Salinity in the Integrated Forecast System

WP 1300: Global Surface Emission Model

WP 1400: IFS Interface

WP 1500: RTTOVS Update

WP 1600: IFS Suite Development

WP 1610: Collocation Software Development

WP 1100 / 1300: SMOS Community Microwave Emission Model

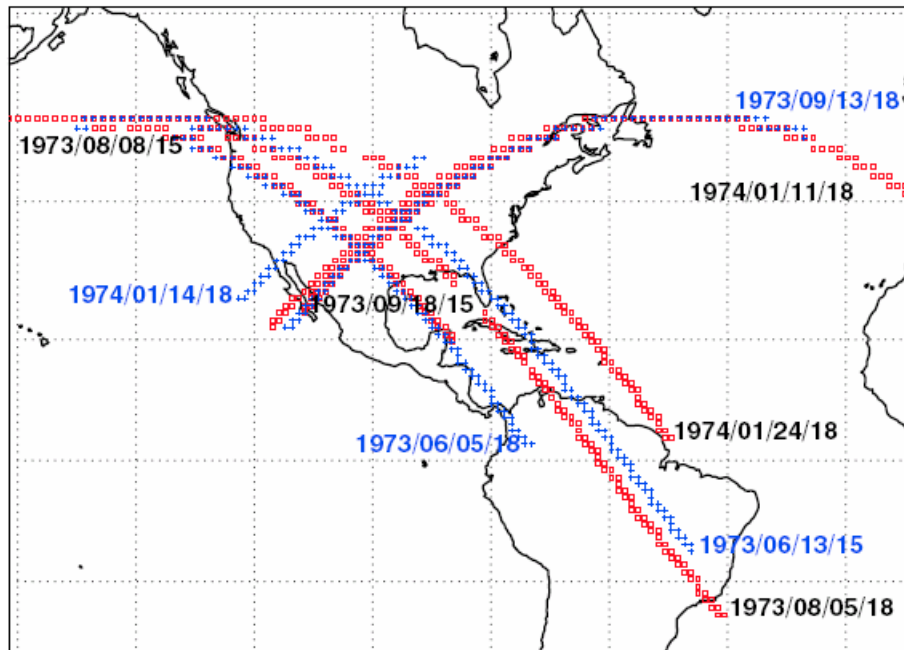
TABLE II

DEFAULT MODEL CONFIGURATION FOR L-BAND AND OPTIONAL MODULES. ALL MODULES ARE DESCRIBED IN SECTION II. VEGETATION PARAMETERS INCLUDE VALUES FOR LOW AND HIGH VEGETATION.

<i>Components</i>	<i>Default Module</i>	<i>Optional Modules</i>		
T_{eff}	Wigneron [22]	Holmes [23]	Choudhury [21]	
ϵ_{soil}	Dobson [25]	Wang-Schmugge [24]		
r_s	Fresnel law	Wilheit [18]		
r_r	Wigneron I [22]	Wegmüller [32]	Wigneron II [22]	Choudhury [30]
vegetation	Kirdyashev [33]	Wigneron [47]	Wegmüller [32]	
snow	Pulliaainen [36]			
atmosphere	Pellarin [48]	Liebe [39]		

<i>Parameters</i>	<i>Default</i>	<i>L-MEB Setup</i>	<i>LSMEM Setup</i>	
sal_{soil} [psu]	0	0	0.65	
sal_{veg} [psu]	6	6	6	
sal_{sea} [psu]	32.5	32.5	-	
r_r - module	Wigneron I [22]	Wigneron II [22]	Wegmüller [32]	
L_c/s or σ [cm]	$L_c/s = 6.0/2.2$	$L_c/s = 6.0/0.15$	$\sigma = 0.5$	
Q [-]	0	0	$f(\sigma)$	
N_{rp}	0	0	2	
VWC [kgm ⁻²] (L,H)	$f(vegtype)$	$f(vegtype)$	(1.0, 4.0)	
ω [-] (L,H)	(0.05, 0.05)	(0. to 0.05, 0.15)	(0.05, 0.05)	
vegetation module	Kirdyashev [33]	Wigneron [47]	Wegmüller [32]	
a_{geo} or b [m ² kg ⁻¹] (L,H)	$a_{geo} = (0.33, 0.66)$	$b = (0.2, 0.33)$	$b = (0.33, 0.33)$	

WP 1100 / 1300: Initial Calibration Using ERA-40 and Skylab



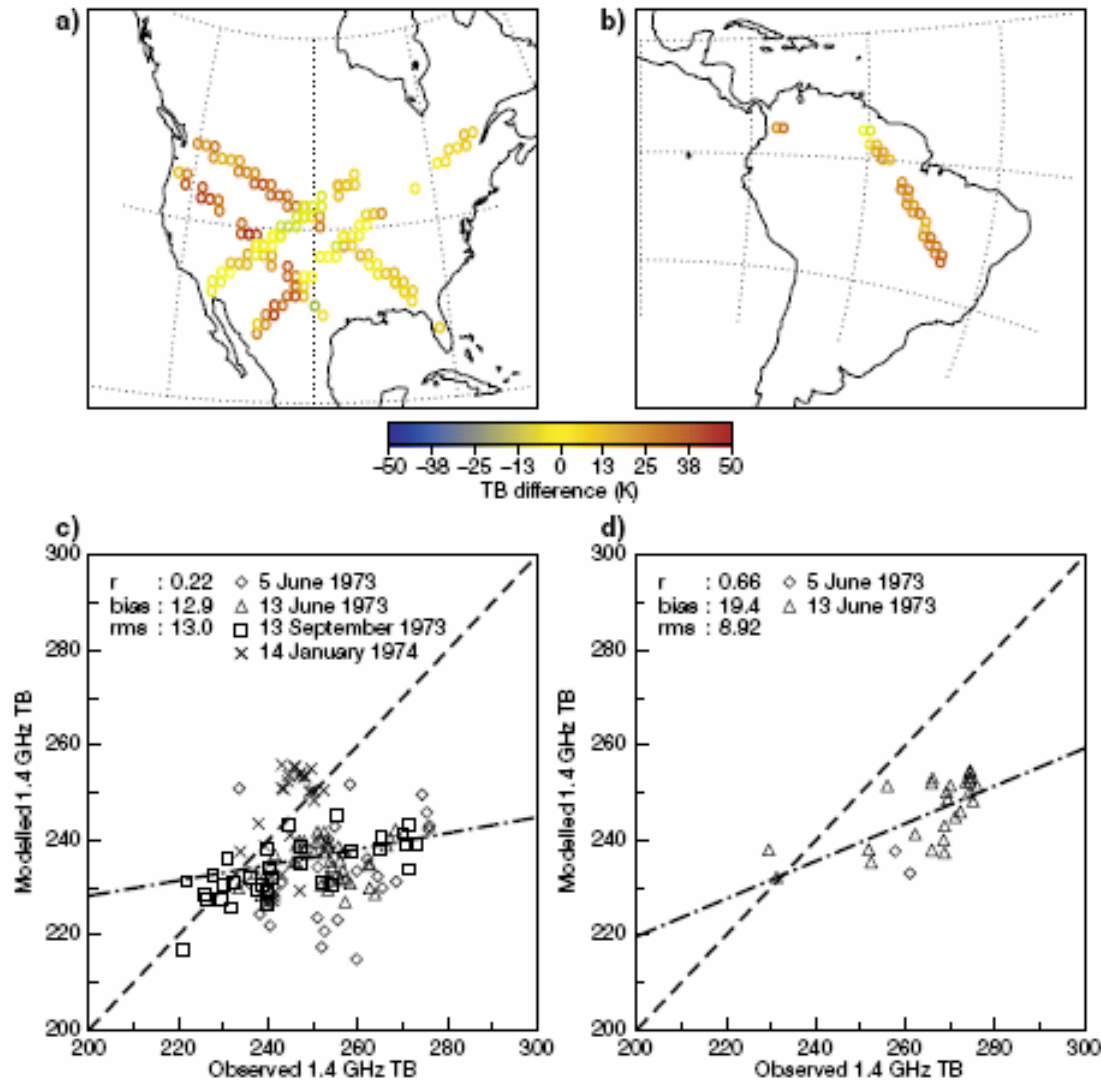
SKYLAB facts:

- launch 14 May 1973
- nominal altitude 435 km
- back on earth 11 July 1977
- data collection required astronaut

S-194 facts:

- L-band radiometer
- nadir looking
- 110 km resolution
- 2.5 km sampling
- most measurements were lost, 9 overpasses could be recovered from print-outs ...

WP 1100 / 1300: Initial Calibration Continued



Data:

- S-194 L-band TB
- ECOCLIMAP LAI
- (C-TESSSEL)
- ERA soil moisture
- ERA soil temperature
- ERA 2 m temperature
- ERA snow depth
- FAO soil types
- (H-TESSSEL)

Calibrating:

- surface roughness,
- vegetation structure coef.
- single scattering albedo

WP 1100 / 1300: Initial Calibration Continued

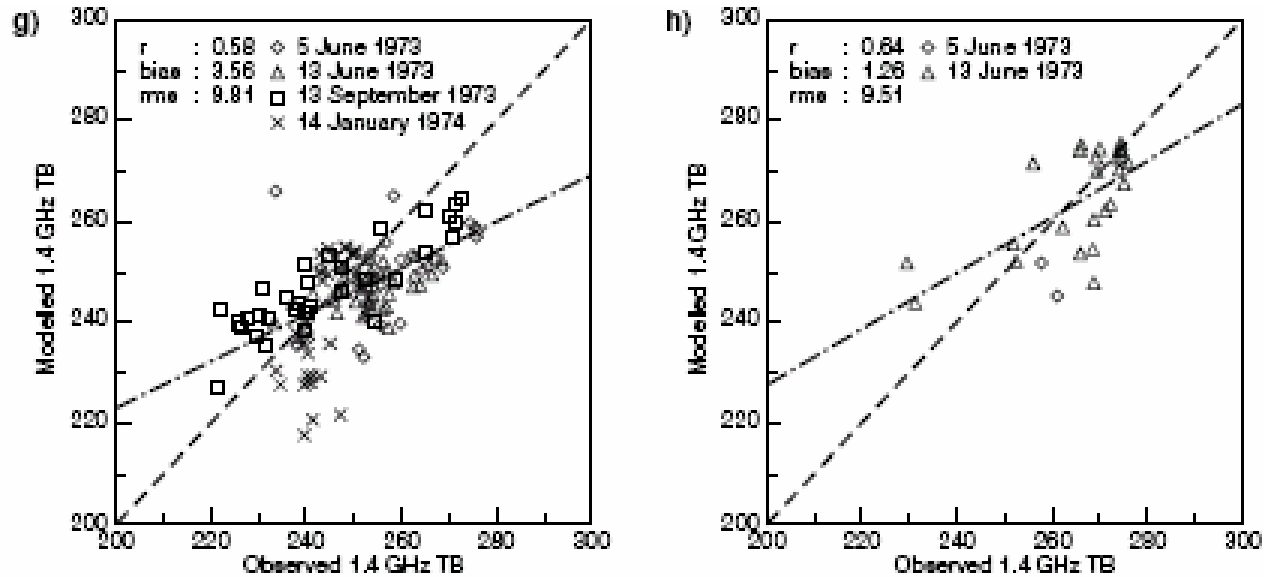
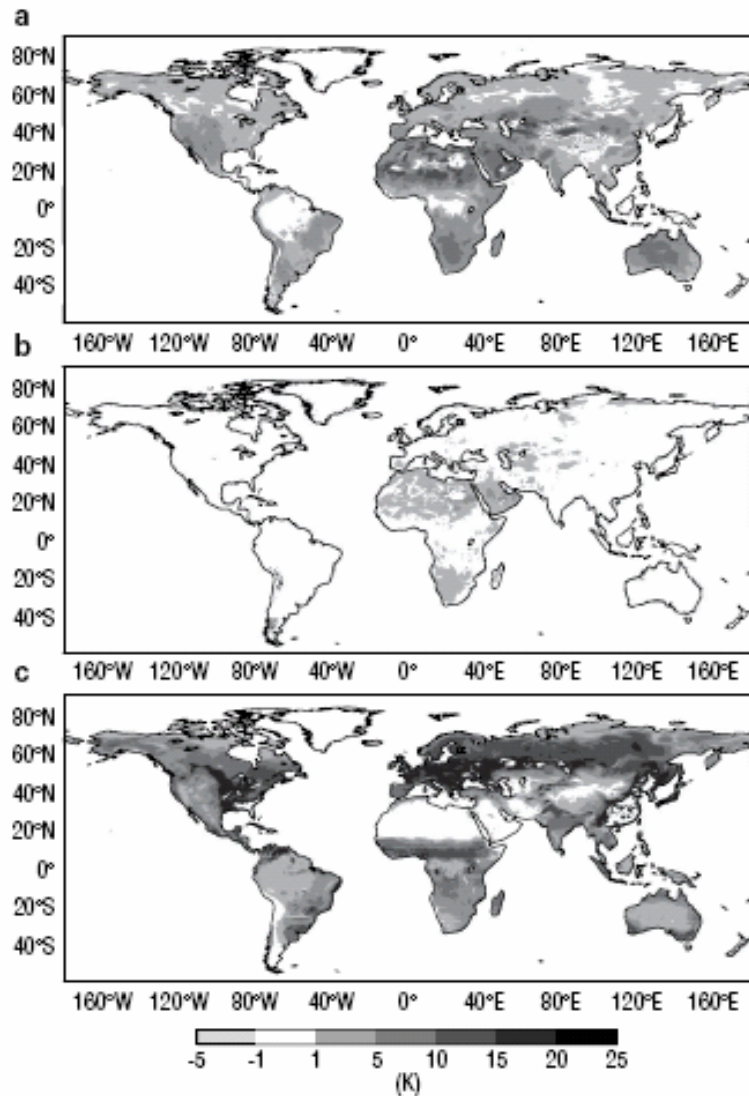


Table 1: CMEM model setup for the calibration and validation computations.

SetUp	Roughness	Vegetation	σ	$\omega(L, H)$	$b(L, H)$	$a_{geo}(L, H)$	$VWC_{trop.}$
A	Wigneron (Eq.4)	Wigneron	0.15	(0.05, 0.15)	(0.2, 0.33)		6
B	Wigneron (Eq.4)	Wigneron	2.2	(0.05, 0.05)	(0.2, 0.33)		6
C	Wigneron (Eq.5)	Wigneron	2.2	(0.05, 0.05)	(0.2, 0.33)		6
D	Wigneron (Eq.5)	Kirdyashev	2.2	(0.05, 0.05)		(0.33, 0.33)	6
E	Wigneron (Eq.5)	Kirdyashev	2.2	(0.05, 0.05)		(0.33, 0.66)	10

WP 1100 / 1300: Sensitivity



L-band (1.4 GHz)

- brightness temperature differences
- h-polarization, 50° incidence angle
- 1 July 2005, 12:00 UTC, DA stream
- dielectric model for the wet soil
([Wang and Schmugge, 1980]-[Dobson et al. 1985])
global mean: 4 K
- effective soil temperature
([Wigneron et al. 2001] – [Wilheit 1978])
maximum < 5 K
- vegetation model
([Wigneron et al. 1995] – [Kirdyashev et al. 1979])
global mean: 8 K

Part I: Monitoring SMOS Brightness Temperatures

WP 1620: Operational Pre-processing Chain

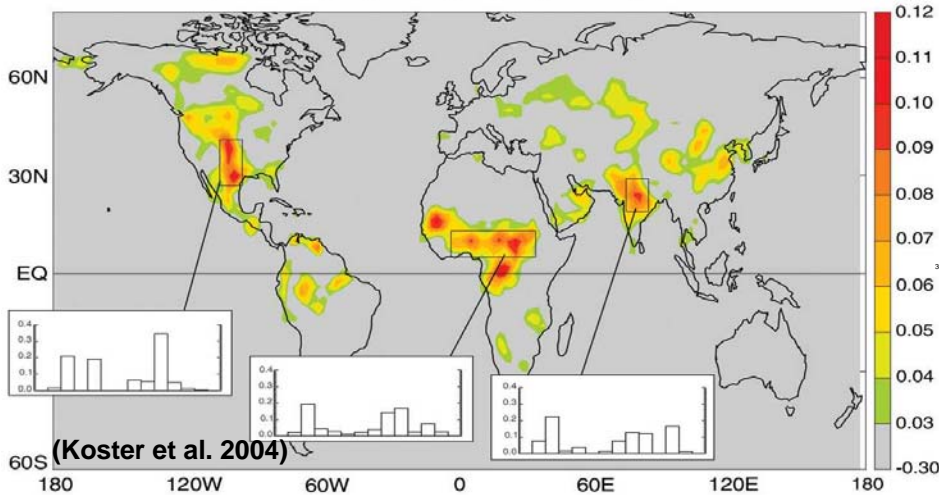
WP 1630: 'Offline' Monitoring Suite

WP 1700: Continuous Monitoring

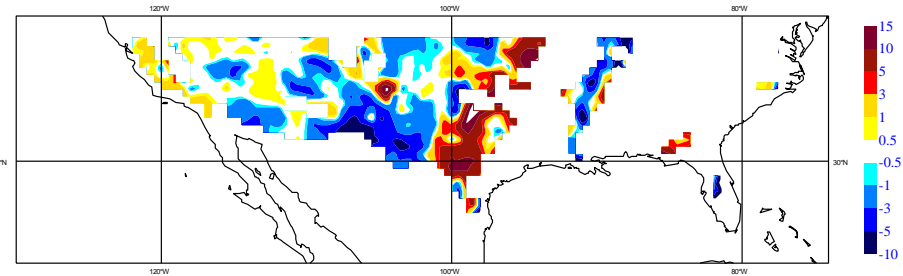
WP 1800: Hot Spot Analysis

Hot Spot Analysis (Land - Atmosphere Coupling)

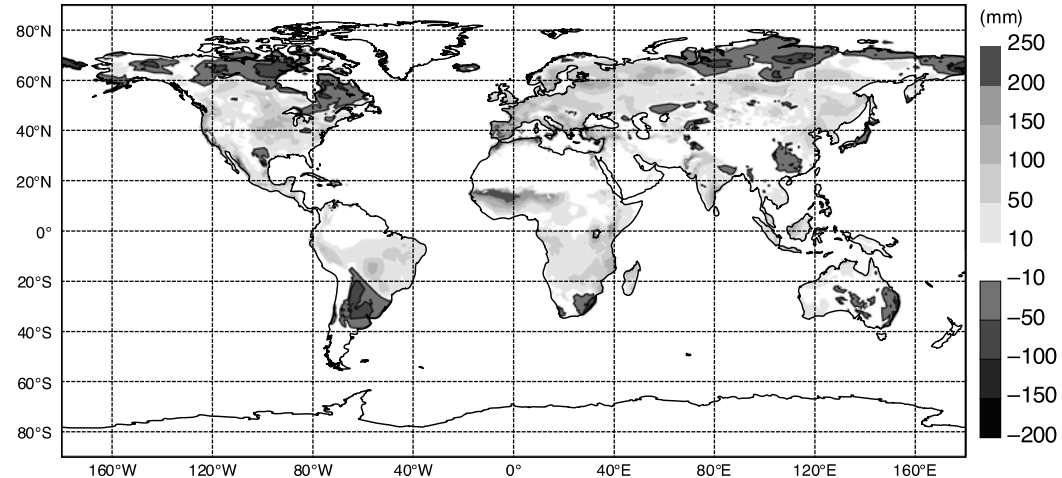
Land-atmosphere coupling strength (JJA), averaged across AGCMs



Model - TMI soil moisture



Accumulated OI analysis increments



Part II: DA Study

WP 2110: Modifying the Extended Kalman Filter

WP 2120: Adjusting the Surface Data Assimilation System

WP 2130: Bias Correction

WP 2200: Assimilation Experiments

WP 2300: Soil Moisture Monitoring

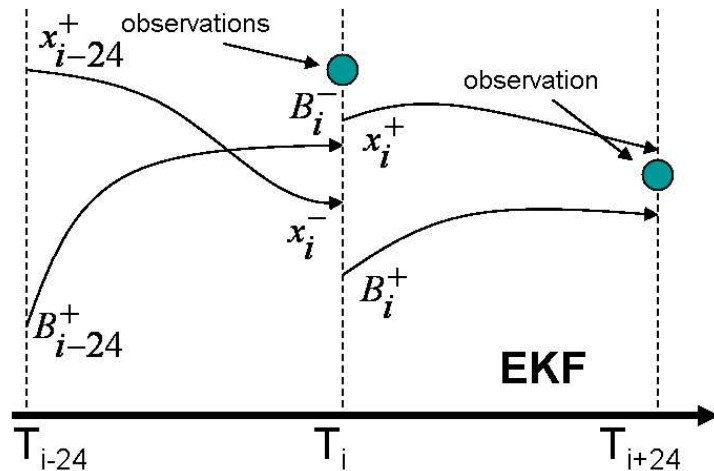
WP 2110: EKF Modifications

Update at T_i :

$$\mathbf{K}_i = \mathbf{B}_i^- \mathbf{H}_i^T [\mathbf{H}_i \mathbf{B}_i^- \mathbf{H}_i^T + \mathbf{R}_i]^{-1}$$

$$\mathbf{x}_i^+ = \mathbf{x}_i^- + \mathbf{K}_i [\mathbf{y}_i - \mathbf{H}_i \mathbf{x}_i^-]$$

$$\mathbf{B}_i^+ = \mathbf{B}_i^- - \mathbf{K}_i \mathbf{H}_i \mathbf{B}_i^-$$



Propagation T_{i-24} to T_i :

$$\mathbf{x}_i^- = \mathbf{f}_{i-24}(\mathbf{x}_{i-24}^+)$$

$$\mathbf{B}_i^- = \mathbf{F}_{i-24} \mathbf{B}_{i-24}^+ \mathbf{F}_{i-24}^T + \mathbf{Q}_{i-24}$$

$$[\mathbf{F}_{i-24}]_{mn} = \left. \frac{\partial f_m}{\partial x_n} \right|_{\mathbf{x}_{i-24}^+}$$

Propagation T_i to T_{i+24} :

$$\mathbf{x}_{i+24}^- = \mathbf{f}_i(\mathbf{x}_i^+)$$

$$\mathbf{B}_{i+24}^- = \mathbf{F}_i \mathbf{B}_i^+ \mathbf{F}_i^T + \mathbf{Q}_i$$

$$[\mathbf{F}_i]_{mn} = \left. \frac{\partial f_m}{\partial x_n} \right|_{\mathbf{x}_i^+}$$

y: observation vector

x: model state vector

H: observation operator

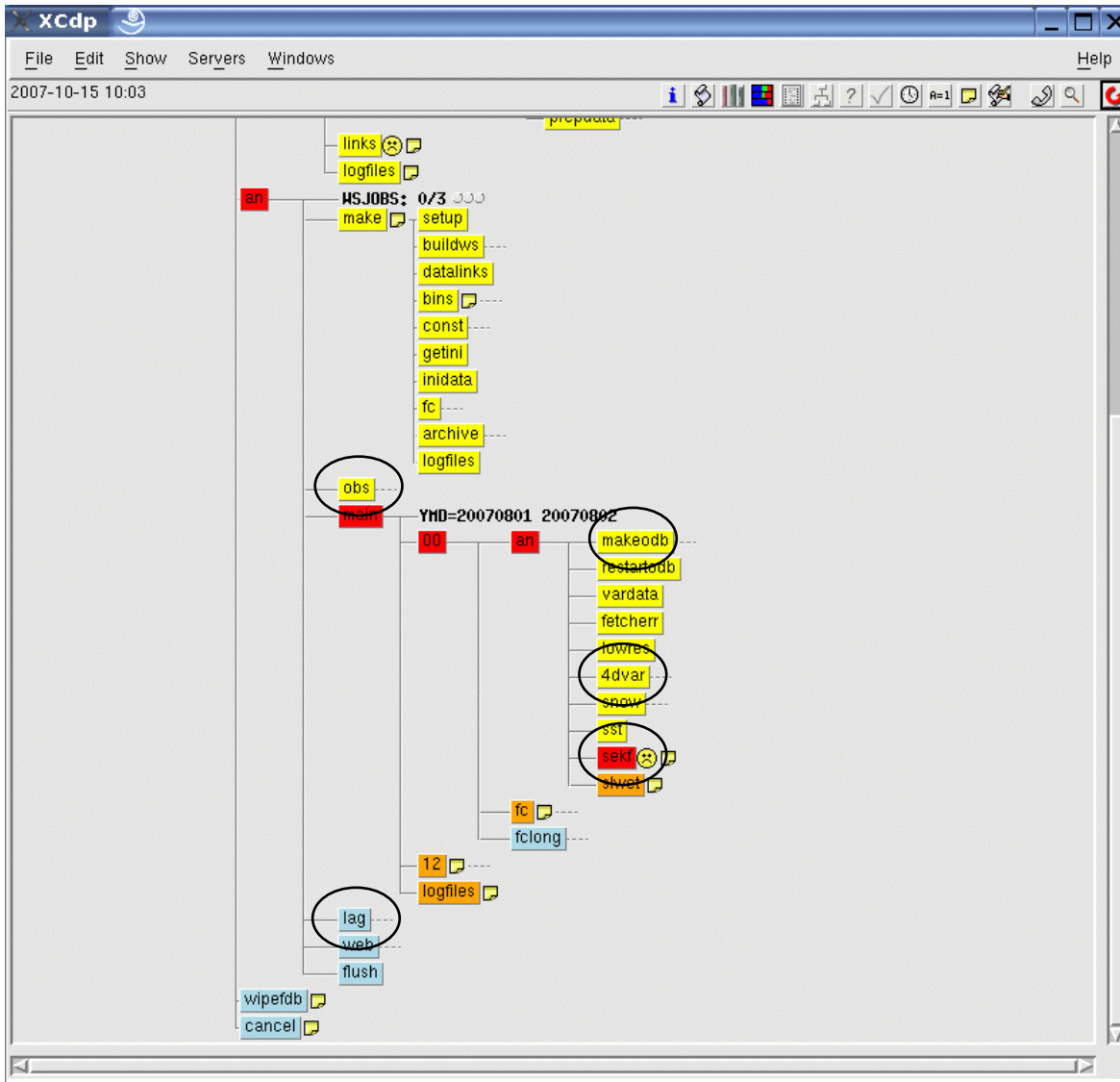
B: background error covariance matrix

Q: model error covariance matrix

R: observation error covariance matrix

F: state transition matrix

WP 1630 & 2120: SDAS Adjustment



Supervisor Monitor Scheduler

Modifications to:

- the observation retrieval
- the observation data base
- the observation handling in the atmospheric 4DVar
- the observation handling in the extended Kalman Filter
- the archiving task

WP 2130: Bias Correction

Systematic errors (or biases) must be removed before the assimilation otherwise biases will propagate in to the analysis (causing global damage in the case of satellites!).

$$\text{Bias} = \text{mean} [Y_{\text{obs}} - H(X_b)]$$

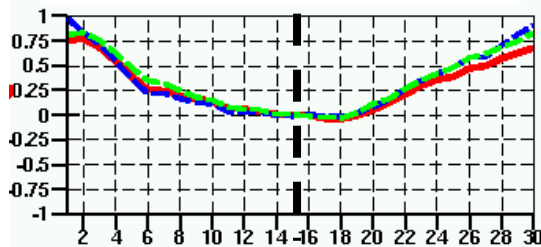
Observed radiance

RT model

Background
Atmospheric state

biases that vary depending on location or air-mass

AMSU-A channel 7

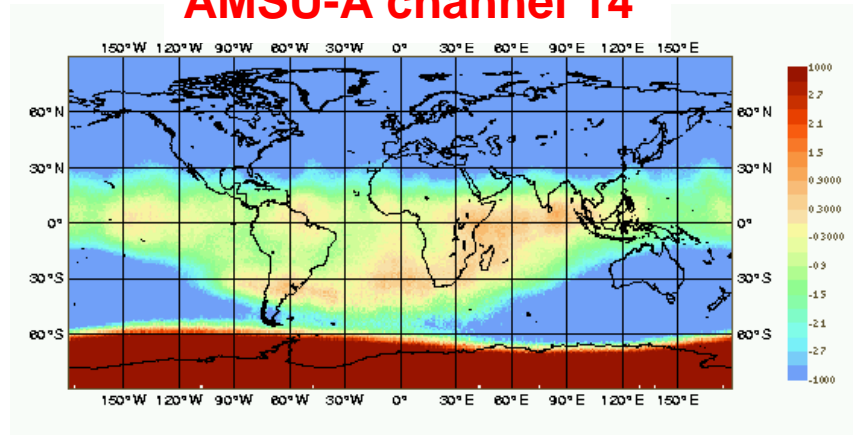


limb

nadir

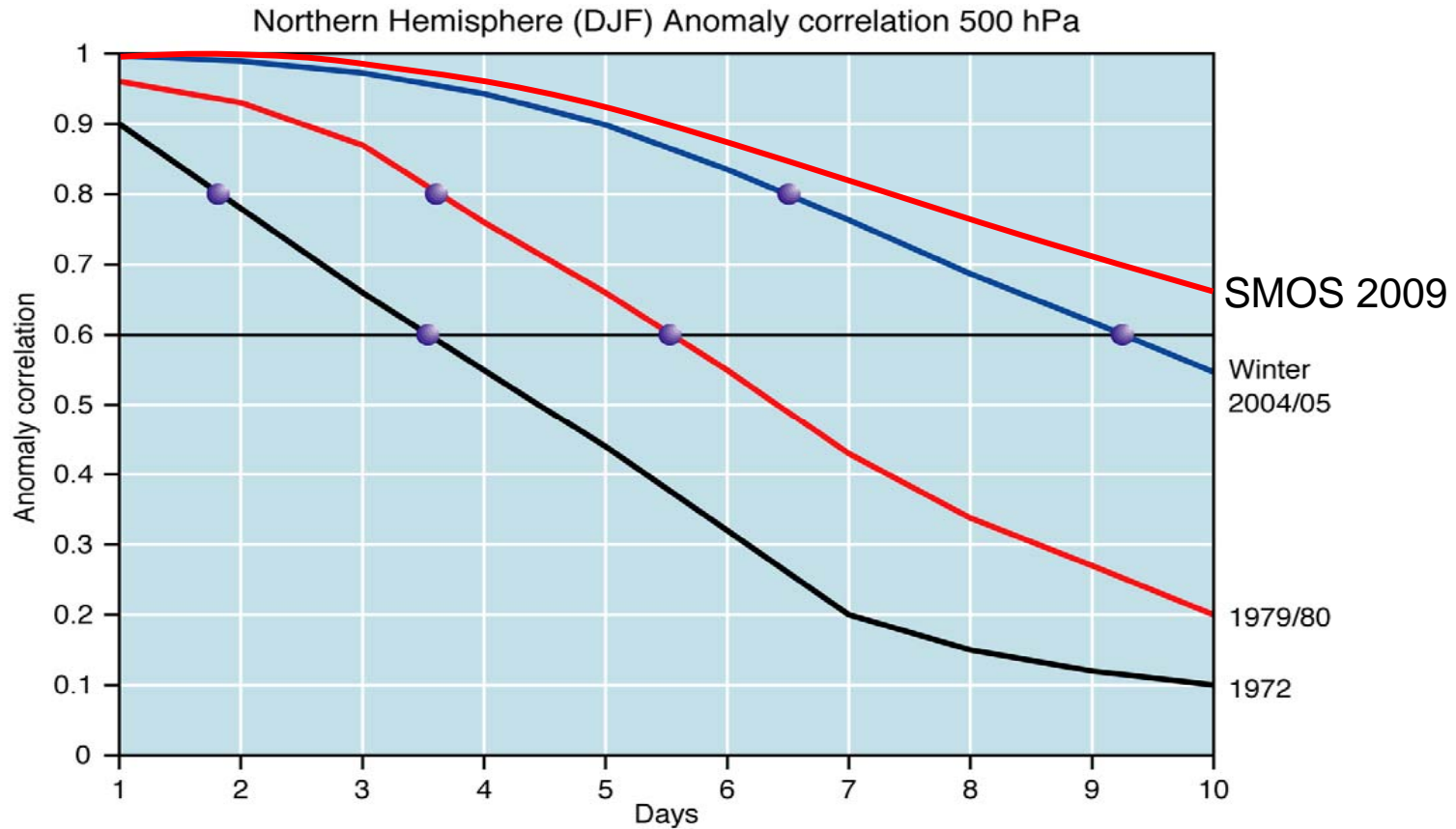
limb

AMSU-A channel 14



biases that vary depending on the Scan position of the satellite instrument

WP 2200: Assimilation Experiments



WP 2300: Soil Moisture Monitoring

first guess departures 01/04/2007

